VIII weekend on Variational Methods and Differential Equations Universit`a di Catania, Catania (Italy) –

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Two positive solutions to

a semilinear spectral problem with

a convex/concave nonlinearity

of variable $q(x)$ -power-type $(q(x)(\geq/\\leq)1)$

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Laplace operator and a nonlinearity of variable $(q(x) - 1)$ -power-type

(1)
$$
-\Delta u = \lambda |u(x)|^{q(x)-2} u(x) + f(x) \quad \text{for } x \in \Omega;
$$

$$
u = 0 \text{ on } \partial\Omega,
$$

with the **variable exponent** $q: \overline{\Omega} \to \mathbb{R}$ which is assumed to be continuous and The nonlinearity $s \mapsto s^{q(x)-1}$: $\mathbb{R}_+ \to \mathbb{R}_+ = [0, \infty)$ is for

 $1 < q(x) \leq 2$ concave $2 \le q(x) < q^* = \frac{N+2}{N-2}$ ($N \ge 3$) **CONVEX**, $q^* = +\infty$ if $N = 1, 2$.

Main Hypothesis: $q : \overline{\Omega} \to \mathbb{R}$ is continuous and such that $1 < q(x) < q^*$ and the (open) sets

> $\Omega_-\stackrel{{\mathrm {\footnotesize def}}}{=} \{x\in\Omega:\,q(x)<2\} \text{ and }$ $\Omega_+ \stackrel{\text{def}}{=} \{x \in \Omega : q(x) > 2\}$

are nonempty.

Laplace operator and a nonlinearity of variable $(q(x) - 1)$ -power-type

(1)
$$
-\Delta u = \lambda |u(x)|^{q(x)-2} u(x) + h(x) \quad \text{for } x \in \Omega; u = 0 \text{ on } \partial\Omega,
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with the **variable exponent** $q : \overline{\Omega} \to \mathbb{R}$ which is assumed to be continuous and The nonlinearity $s \mapsto s^{q(x)-1}$: $\mathbb{R}_+ \to \mathbb{R}_+ = [0, \infty)$ is for

 $1 < q(x) \leq 2$ concave. $2 \le q(x) < q^* = \frac{2N}{N-2}$ ($N \ge 3$) convex, $q^* = +\infty$ if $N = 1, 2$.

Previous works (e.g. by P.-L. Lions) consider a sum $g(s) = g_1(s) + g_2(s)$ indepedent of $x \in \Omega$ with $g_1: \mathbb{R}_+ \to \mathbb{R}_+$ concave and $g_2: \mathbb{R}_+ \to \mathbb{R}_+$ convex. Under some very natural conditions on the behavior of the functions $g_1, g_2 : \mathbb{R}_+ \to \mathbb{R}_+$ of $s \in (0, \infty)$ near zero $(s \rightarrow 0+)$ and at infinity $(s \rightarrow +\infty)$, the following diagram is obtained:

Case 3. $f'(0) = 1, f(t) < t$ for $t > 0$, t small. *Example.* $f(t) = t(1 - \sin t) + t^p (1 < p < (N + 2)/(N - 2)).$

POSITIVE SOLUTIONS OF SEMILINEAR ELLIPTIC EQUATIONS

Case 4. $\lim_{t\to 0_+} f(t)t^{-1} = +\infty$.
Example. $f(t) = \sqrt{t} + t^p (1 < p < (N+2)/(N-2))$.

N

 Ω C \mathbb{R}^N $g(x) < 2-8$ $q(x) > 2 + 8$ $\Omega_{\mathcal{S}^-}$ $g(x) = 2$ $8>0$ small

Main Hypothesis: $q : \overline{\Omega} \to \mathbb{R}$ is continuous and such that $1 < q(x) < q^*$ and the (open) sets

> $\Omega_{-} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) < 2\}$ and $\Omega_+ \stackrel{\text{def}}{=} \{x \in \Omega : q(x) > 2\}$

are nonempty.

If $\delta > 0$ is small enough, then both sets

$$
\Omega_{\delta-} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) < 2 - \delta\} \neq \emptyset \text{ and}
$$
\n
$$
\Omega_{\delta+} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) > 2 + \delta\} \neq \emptyset
$$

are nonempty. $0 < \delta < \min\{2 - q^{(-)}, q^{(+)} - 2\}.$ (H_q)

$$
1 < q^{(-)} \stackrel{\text{def}}{=} \min_{\overline{\Omega}} q(x) < p(x) \equiv p = 2
$$

$$
< q^{(+)} \stackrel{\text{def}}{=} \max_{\overline{\Omega}} q(x) < \infty.
$$

We fix $\delta > 0$ small enough, such that both (open) sets

$$
\Omega_{\delta-} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) < 2 - \delta\} \neq \emptyset \text{ and}
$$
\n
$$
\Omega_{\delta+} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) > 2 + \delta\} \neq \emptyset
$$

are nonempty.

Next, we estimate the full nonlinearity

(2)
$$
f(x,s) \equiv f_{\lambda}(x,s) = \lambda |s|^{q(x)-2} s + h(x).
$$

from below by a **concave** function, for $(x, s) \in \Omega \times \mathbb{R}_+$:

(3)
$$
f_1(x, s) = f_{1,\lambda}(x, s) =
$$

$$
\begin{cases} \lambda \cdot (\min\{s, 1\})^{q(x)-1} & \text{if } q(x) < 2 - \delta \, ; \\ 0 & \text{if } q(x) \ge 2 - \delta \, . \end{cases}
$$

Hence, $f_1(x, s) = \lambda \cdot (\min\{s, 1\})^{q(x)-1} \cdot \chi_{\Omega_{\delta-}}(x), s \ge 0.$

Proposition 1. Given any number $\lambda > 0$ and any nonnegative function $h \in L^{\infty}(\Omega)$, i.e., $h \in [L^{\infty}(\Omega)]_{+}$, the Dirichlet problem

(4)
$$
-\Delta u = \lambda f_1(x, s) + h(x) \quad \text{for } x \in \Omega; u = 0 \text{ on } \partial\Omega,
$$

possesses a unique positive solution $u \equiv u_{\lambda} \in W_0^{1,2}(\Omega)$.

stability This result is proved in P. Takáč (NA 1990), P. Hess (Theorem 5.1, 1991 Pitman 1991), motivated by M.A. Krasnosel'skij (1964).

We begin with the following two a priori results (bounds) on the set $\mathcal{S} \subset \mathbb{R}_+ \times \big[W \big]$ 1,2 $\left[\begin{smallmatrix} 1,2\ 0 \end{smallmatrix} \left(\Omega \right) \right]$ $+$ of all pairs $(\lambda, u) \in \mathbb{R} \times W_0^{1,2}$ $\mathcal{L}_0^{1,2}(\Omega)$ such that $\lambda \in \mathbb{R}_+$, $u \in W_0^{1,2}$ $\zeta_0^{1,2}(\Omega)$ is nonnegative in Ω, i.e., $u \in \left[W\right]$ 1,2 $\left[0 \atop 0}^{1,2}(\Omega)\right]$ $+$, and

(5)
$$
-\Delta u = \lambda u(x)^{q(x)-1} + h(x) \quad \text{for } x \in \Omega; u = 0 \text{ on } \partial\Omega.
$$

We assume that $h \in L^{\infty}(\Omega)$ is a nonnegative function, i.e., $h \in [L^{\infty}(\Omega)]_{+}$. We set, for $(x, s) \in \Omega \times \mathbb{R}$.

$$
f(x,s) \equiv f_{\lambda}(x,s) = \lambda |s|^{q(x)-2} s + h(x).
$$

Proposition 2. There exists a number $\lambda^* \geq 0$ such that $(\lambda, u) \in S \implies \lambda \leq \lambda^*$. Equivalently, we have

$$
\lambda^* \stackrel{\text{def}}{=} \sup_{(\lambda, u) \in \mathcal{S}} \lambda < \infty \, .
$$

Proof: Step 1. Consider eq. (5) with $\lambda = \lambda_0 = 0$ and $h = f_0 \in [L^{\infty}(\Omega)]_+$ supported in

 Ω_{+} def $\stackrel{\text{def}}{=} \{x \in \Omega: \, q(x) > 2\} \, , \, f_0 \not\equiv 0 \, \text{ in } \, \Omega_+ , \text{ say, } \, f_0(x) > 0 \, .$ for

$$
x \in K_{\delta} \subset \Omega_{\delta+} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) > 2 + \delta\},\
$$

where K_{δ} is a compact set with nonempty interior.

Denote the weak solution by $u_0 \in W_0^{1,2}$ $L^{1,2}(\Omega)$,

$$
u_0(x) \stackrel{\text{def}}{=} [(-\Delta)^{-1} f_0](x) = \int_{\Omega} G(x, y) f_0(y) dy
$$

=
$$
\int_{\Omega_+} G(x, y) f_0(y) dy \quad \text{for } x \in \Omega.
$$

Hence, by regularity, $u_0 \in C^{1,\theta}(\overline{\Omega})$, $0 < \theta < 1$. It satisfies the **Hopf maximum principle**:

(HMP) $u_0 > 0$ in Ω and $\frac{\partial u_0}{\partial \nu}(x) < 0$ on $\partial \Omega$.

The pair $(\phi, g) = (u_0, f_0)$ verifies the basic Poisson equation

(6)
$$
-\Delta \phi = g(x)
$$
 for $x \in \Omega$; $\phi = 0$ on $\partial \Omega$.

The solution $\phi \in C^{1,\theta}(\overline{\Omega})$, $0 < \theta < 1$, satisfies the Hopf maximum principle:

(HMP) $\phi > 0$ in Ω and $\frac{\partial \phi}{\partial u}(x) < 0$ on $\partial \Omega$.

Furthermore, $g \in [L^{\infty}(\Omega)]_{+}$ is supported in $M_{\delta} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) \geq 2 + \delta\} \supset \Omega_{\delta+}$, hence, $q(x) > 0 \implies q(x) \geq 2 + \delta$.

Main Hypothesis: $q : \overline{\Omega} \to \mathbb{R}$ is continuous and such that $1 < q(x) < q^*$ and the (open) sets

$$
\Omega_{\delta-} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) < 2 - \delta\} \neq \emptyset \text{ and}
$$
\n
$$
\Omega_{\delta+} \stackrel{\text{def}}{=} \{x \in \Omega : q(x) > 2 + \delta\} \neq \emptyset
$$

 $0 < \delta < \min\{2-q^{(-)}, q^{(+)}-2\}.$

are **nonempty**. (H_q)

Step 2. A priori estimates for the Dirichlet problem

$$
\begin{array}{ll}\n\text{(1)} & -\Delta u = \lambda \left[u(x) \right]^{q(x)-1} + h(x) & \text{for } x \in \Omega \,; \\
u = 0 \text{ on } \partial\Omega, & \text{and } u > 0 \text{ in } \Omega \,; \n\end{array}
$$

with the **variable exponent** $q : \overline{\Omega} \to \mathbb{R}$ which is assumed to be continuous.

In accordance with Step 1, we work in the set Ω_{+} def $\stackrel{\text{def}}{=} \{x \in \Omega : q(x) > 2\}.$ The well-known identity, for $u, \phi \in W_0^{1,2}$ $L^{1,2}(\Omega)$,

$$
\int_{\Omega} (-\Delta u(x)) \cdot \phi(x) dx = \int_{\Omega} u(x) \cdot (-\Delta \phi(x)) dx,
$$
lds

yields

$$
\lambda \int_{\Omega} [u(x)]^{q(x)-1} \cdot \phi(x) dx
$$

+
$$
\int_{\Omega} h(x) \cdot \phi(x) dx = \int_{\Omega} u(x) \cdot g(x) dx
$$

=
$$
\int_{\{x \in \Omega : g(x) > 0\}} u(x) \cdot g(x) dx
$$

=
$$
\int_{\{x \in \Omega : q(x) \ge 2 + \delta\}} u(x) \cdot g(x) dx.
$$

```
Since u > 0 in \Omega, the a priori estimates on
"a suitable L^p-norm" of u are obtained from
the last equation in a way analogous to that developed
in the articles by R. D. Nussbaum (1975),
H. Brézis and R. E. L. Turner (1977), and
D. G. Figueiredo, P.-L. Lions, and
R. D. Nussbaum (1982).
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We decompose the nonnegative function $u: \Omega \to \mathbb{R}$ as

 $\epsilon \cdot u(x)$ $= \left[(\epsilon \cdot u(x))^{q(x)-1} \cdot \phi(x) \right]^{1/(q(x)-1)} \cdot \phi(x)^{-1/(q(x)-1)},$

with $\epsilon > 0$ and apply **Young's inequality** to estimate the integral on the right-hand side of eq. (7) to get

$$
\int_{\Omega} u(x) \cdot g(x) dx = \int_{\Omega} \epsilon u(x) \cdot \epsilon^{-1} g(x) dx
$$
\n
$$
\leq \int_{\Omega} \frac{\epsilon^{q(x)-1}}{q(x)-1} [u(x)]^{q(x)-1} \phi(x) dx
$$
\n
$$
+ \int_{\Omega} \frac{q(x)-2}{q(x)-1} \cdot \epsilon^{-(q(x)-1)/(q(x)-2)} \times [\phi(x)^{-1} \cdot g(x)^{q(x)-1}]^{1/(q(x)-2)} dx.
$$

Substituting

$$
\varepsilon = \epsilon^{q(x)-1}/(q(x)-1) > 0
$$

we get

$$
\epsilon \equiv \epsilon(x) = [\epsilon(q(x) - 1)]^{1/(q(x) - 1)}
$$

.

Consequently, inequality (8) becomes

$$
\int_{\Omega} u(x) \cdot g(x) dx
$$
\n
$$
\leq \varepsilon \cdot \int_{\Omega} [u(x)]^{q(x)-1} \cdot \phi(x) dx
$$
\n
$$
+ \int_{\Omega} \frac{q(x)-2}{q(x)-1} \cdot \varepsilon^{-1/(q(x)-2)} (q(x)-1)^{-1/(q(x)-2)}
$$
\n
$$
\times [\phi(x)^{-1/(q(x)-1)} \cdot g(x)]^{(q(x)-1)/(q(x)-2)} dx
$$
\n
$$
= \varepsilon \cdot \int_{\Omega} [u(x)]^{q(x)-1} \cdot \phi(x) dx
$$
\n(9)\n
$$
+ \int_{\Omega} \varepsilon^{-1/(q(x)-2)} \cdot \frac{q(x)-2}{(q(x)-1)^{1+\frac{1}{q(x)-2}}}
$$
\n
$$
\times [\phi(x)^{-1} \cdot g(x)^{q(x)-1}]^{1/(q(x)-2)} dx
$$
\n
$$
= \varepsilon \cdot \int_{\Omega} [u(x)]^{q(x)-1} \cdot \phi(x) dx
$$
\n
$$
+ \int_{\Omega} \varepsilon^{-1/(q(x)-2)} \cdot (q(x)-2) (q(x)-1)^{-\frac{(q(x)-1)}{(q(x)-2)}} \times [\phi(x)^{-1} \cdot g(x)^{q(x)-1}]^{1/(q(x)-2)} dx.
$$

We estimate the left-hand side of eq. (7) by ineq. (9) as follows, provided $0 < \varepsilon < \lambda$.

We recall that, for all $x \in \Omega$ we have

$$
g(x) > 0 \implies q(x) \ge 2 + \delta.
$$

$$
(\lambda - \varepsilon) \int_{\Omega} [u(x)]^{q(x)-1} \cdot \phi(x) dx
$$

+
$$
\int_{\Omega} f(x) \cdot \phi(x) dx \le C_{\varepsilon} < \infty \quad \text{where}
$$

(10)

$$
C_{\varepsilon} \stackrel{\text{def}}{=} \int_{\Omega} \varepsilon^{-1/(q(x)-2)} \cdot \frac{q(x)-2}{(q(x)-1)^{(q(x)-2)}}
$$

$$
\times \left[\phi(x)^{-1} \cdot g(x)^{q(x)-1} \right]^{1/(q(x)-2)} dx.
$$

This inequality clearly imposes an upper bound on the solution u for any fixed value of $\lambda \ge \lambda_0 \equiv \text{const} > 0$.

It, ineq. (10) , remains valid even if u is only a nonnegative subsolution, i.e., if

(11)
$$
-\Delta u \ge \lambda [u(x)]^{q(x)-1} + h(x) \quad \text{for } x \in \Omega ;
$$

$$
u = 0 \text{ on } \partial \Omega, \text{ and } u > 0 \text{ in } \Omega.
$$

Theorem 1. Assume that the **variable exponent** q : $\overline{\Omega} \to \mathbb{R}$ is a continuous function that satisfies hypothesis (H_q)

$$
1 < q^{(-)} \stackrel{\text{def}}{=} \min_{\overline{\Omega}} q(x) < p(x) \equiv p = 2
$$

$$
< q^{(+)} \stackrel{\text{def}}{=} \max_{\overline{\Omega}} q(x) < \infty.
$$

In addition, let $0 < \varepsilon < \lambda < \infty$.

Assume that $u\in C^1_0(\overline{\Omega})=C^1_0(\overline{\Omega})\cap W^{1,2}_0$ $\int_0^1 f^{(1,2)}(\Omega)$ is any nonnegative subsolution to the Dirichlet problem (1), such that u verifies the Hopf maximum principle:

(HMP) $u_0 > 0$ in Ω and $\frac{\partial u_0}{\partial \nu}(x) < 0$ on $\partial \Omega$,

together with $u \geq u_\varepsilon$ in Ω , where $u_\varepsilon \in C^1_0(\overline{\Omega})$ is the unique positive solution constructed in Proposition 1 for the concave nonlinearity (2) and (3).

Then this subsolution, u , obeys the a priori estimate (10) above.

